

Influence of asymmetric processing delays on the localization ability of bimodal CI/HA users

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Abstract

Under optimal hearing conditions the normal-hearing auditory system can perceive interaural time differences (ITD) as little as 10 μ s. Due to physiological limitations, the largest occurring ITD is about 700 μ s. Differences in processing latencies of digital hearing aids (HA) and cochlear implants (CI) can be as high as 9 ms in bimodal users. These differences result in an interaural stimulation timing mismatch that superimposes physiologically occurring ITDs. This interaural stimulation timing mismatch could account for the reduced sound localization performance in bimodal users, which has been reported by other authors. To investigate this hypothesis, we conducted localization tests in bimodal CI/HA users with and without a compensated stimulation timing mismatch. For this, we delayed the CI stimulation according to the individual HA processing latency by a portable, programmable delay line based on a microcontroller. First, an initial sound localization test without compensation was conducted. Then, the delay line was activated. After a familiarization period to the delay line the test was repeated. The results show a highly significant improvement of the localization ability in the horizontal plane after compensation.

Keywords: Localization, bimodal stimulation, stimulation timing

1 INTRODUCTION

In bimodal users of Cochlear Implants (CI) and hearing aids (HA) the processing delays between both devices are currently not synchronized. In a previous study it could be shown, that the processing delay of MED-EL CI systems τ_{CI} is relatively similar to the physiological delay in normal hearing ears. In contrast, the processing delay of HA τ_{HA} is mostly frequency independent and several milliseconds large. Because HA processing is done in front of the physiological processing in the ear, a device delay mismatch in the order of τ_{HA} occurs in bimodal MED-EL CI/HA users [1]. The measured values of τ_{HA} are in accordance with other studies reporting HA processing delays between 3 and 11 ms [2]. For the identification of syllables Stone & Moore have shown that delays below 15 ms are relatively uncritical [3], this robustness can not be assumed for other mechanisms of binaural hearing. Especially in sound localization, experimental results suggest that bimodal users perform poorer than e.g. bilateral HA users or bilateral CI users [4]. A reason for this could be the device delay mismatch between CI and HA, since the normal hearing auditory system uses interaural time differences (ITD) in the temporal fine structure (TFS) and in the amplitude envelope (ENV) for sound localization. These cues, already diminished by the signal processing of the CI, are likely to be further deteriorated by the superimposed temporal asymmetry between both devices. Even though the auditory system can compensate for static timing asymmetries to some extent, as shown by Trapeau and Schönwiesner [5], plasticity of the auditory system towards asymmetries in the order of several milliseconds has not been investigated. The hypothesis of this study is, that sound localization accuracy of bimodal users will increase, if the device delay mismatch is reduced.

2 METHODS

2.1 Test subjects

Nine adult bimodal test subjects participated in the localization experiments (age: 51.8 ± 13.0 years). The subjects had mild to severe sensorineural or combined hearing loss on the ear provided with the HA and no measurable residual acoustic hearing on the ear provided with the CI. The criteria for inclusion in the localization tests were the following:

1. everyday combined CI and HA use
2. a minimum 50% correct score on the Freiburg monosyllabic test at 65 dB SPL on CI and HA

The work described was conducted in accordance with the Declaration of Helsinki. The approval by the ethics committee of the University of Freiburg was obtained before testing (89/17). Informed consent was obtained by all participants.

2.2 Delay line

To partly compensate for the timing asymmetry between CI and HA stimulation timing, a programmable, portable delay line (DL) was designed based on a microprocessor platform (Arduino DUE). With this DL the input to the CI was delayed according to the HA processing latency τ_{HA} measured with the ACAM 5 HA analyzer (Acousticon GmbH, Reinheim, Germany). The delay was realized by implementing a circular buffer on the microprocessor which allowed to delay the incoming signals by integer multiples of the sampling time T . With a sampling rate of $F_s = 48$ kHz, T is 20.8 μ s. Since the analog-digital converters and digital-analog converters also need additional clock cycles for their conversions an offset of 50 μ s has to be added to the programmed delay. The complete setup for delaying the input to the CI consisted of four components. At first the acoustic signal was captured by an OPUS2 CI audio processor from MED-EL (Innsbruck, Austria) without additional signal processing and therefore no additional delay. The audio processor was connected to a microphone tester, usually used to test the microphones of the audio processors by CI fitting specialists. This microphone tester is an analog amplifier which introduces no remarkable delay to the processing chain. The output of the microphone tester was connected to the DL where the signal was delayed according to the programmed delay. The DL output was fed into the auxiliary input of a second OPUS2 audio processor with the

internal microphones deactivated to avoid non delayed input. This second, silent OPUS2 was programmed with the subjects everyday programming. For subjects HA, settings were not changed. A schematic of the processing chain can be seen in figure 1.

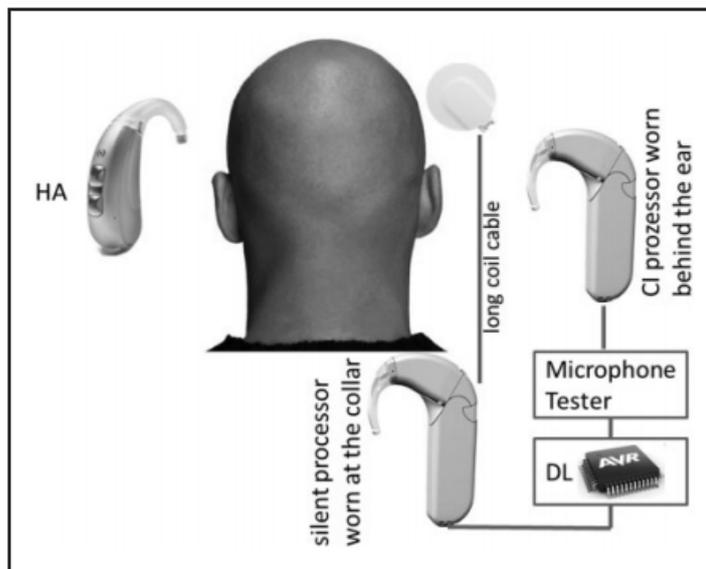


Figure 1. Schematic setup for delaying CI stimulation

2.3 Stimuli and Test environment

The subjects were seated in an audiometric booth with seven loudspeakers (Genelec 8030A) arranged in the frontal horizontal hemisphere between -90° and 90° at intervals of 30° with a distance of 1 m from the subjects and at the height of the subjects ears. The speakers were labeled with numbers 1 to 7 according to 2.

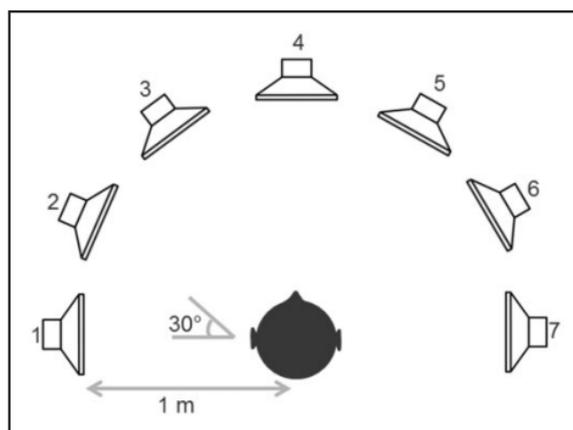


Figure 2. Loudspeaker arrangement for localization tests

The stimuli consisted of 200 ms bursts of white noise bandpass filtered between 125 and 6000 Hz with eight-pole butterworth filters and on- and offset ramps of 20 ms as described by [6]. The stimuli were presented

at a level of 65 dB(A). The subjects were instructed to center their head on loudspeaker number 4 and to refrain from head movements throughout testing. Subjects entered their response to the stimuli with a wireless bluetooth keypad containing the numbers corresponding to the speaker numbers.

2.4 Experimental procedures

Each subject underwent two localization tests, each consisting of 140 stimulus presentations resulting in 20 presentations per speaker per test. The first localization test was conducted with the DLs delay set to 0 ms. Although this test could have been conducted without the DL, it was applied to ensure similar testing conditions between tests. As described above a programmed delay of 0 ms still includes the DLs processing delay of 50 μ s, which is further seen as negligible. After finishing the first test the DL was programmed to the subject specific τ_{HA} . To allow some familiarization to the change in stimulation timing, the subjects were instructed to go for a walk outside the lab for 45 minutes while paying attention to the perceived everyday sound sources (e.g. traffic or conversations). After this period the subjects returned to the lab and were presented with a 15 minute segment of TV news from the night before so that similar training for all subjects could be ensured. After this familiarization period with a total duration of one hour, the second localization test was conducted.

2.5 Data analysis

Root mean square (rms) errors were calculated by the formula proposed by Rakerd and Hartmann [7].

$$D = A \sqrt{\frac{1}{M} \sum_{i=1}^M (r_i - k)^2} \quad (1)$$

In equation 1, A is the angle between loudspeakers (i.e. 30°) and M is the total number of stimuli presented. The parameter r_i corresponds to the response in terms of a speaker number and k is the target speaker, also in terms of the respective speaker number. Rms errors were calculated for every loudspeaker to further investigate the effect of a compensation of timing mismatch. For this purpose equation 1 was used with a fixed k for every loudspeaker over a total of 20 presentation per speaker. Before the analysis, the data was normalized so that the side, where the subjects used their CI was always the left side (i.e. -90°) for better comparability. Because of the small number of data points per subject and speaker no statistic tests were applied.

3 RESULTS

The results for rms errors across all seven speakers show a highly significant improvement in localization ability after activation of the delay line. Details can be found in [8]. In Figure 3 the rms errors for every loudspeaker are shown as boxplots without active use of the DL (blue) and after using the DL for an hour (green). The red lines represent the median and the lower and upper edges of the boxes represent the first and third quartile. The r axis corresponds to the rms error and the θ axis is the respective loudspeaker position.

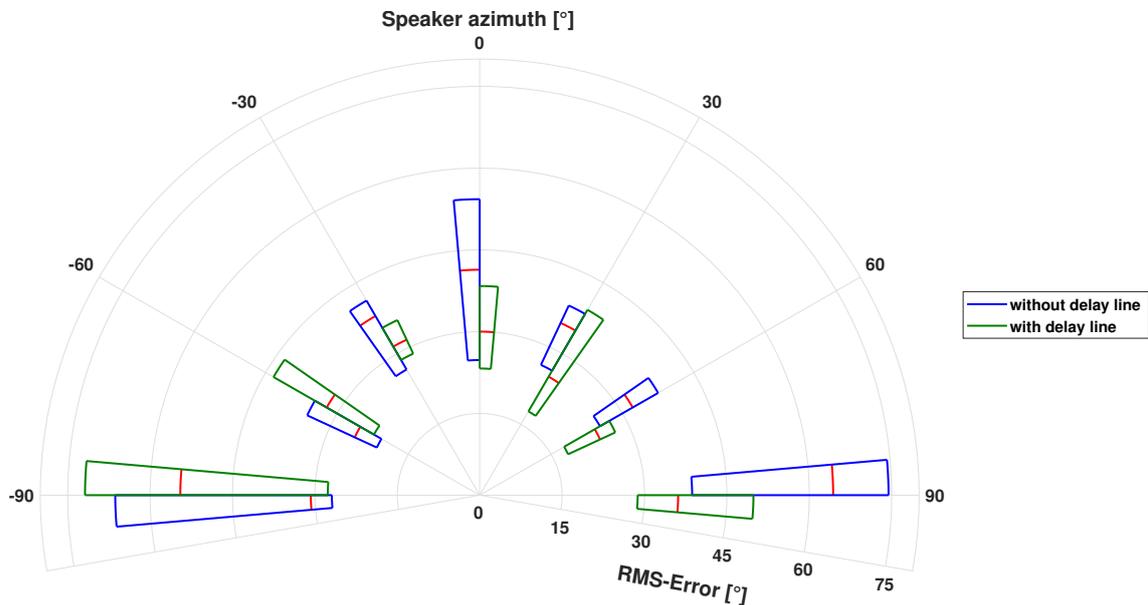


Figure 3. Speaker dependent rms error [°] before and after application of DL (CI always at -90°)

The median rms error for all loudspeakers except for -60° and -90° show an improvement in localization accuracy after employment of the DL, with the biggest improvement of about 30° being at 90° . Further there is a decrease of the interquartile range in almost all of the loudspeakers where localization improved with application of the DL.

For the loudspeaker at the CI side (thus at -90°) of the bimodal listeners a decrease in localization accuracy after application of the DL can be seen. This is hypothesized to be due to the impact of the delayed CI stimulation in contrast with the subjects everyday condition without the applied delay. Longer familiarization periods could possibly reduce this negative effect.

4 CONCLUSIONS

In this refinement of the previously published data [8] it could be shown that analysis of localization ability on a finer scale yields a better understanding of the improvement in localization ability through a compensation of a device delay mismatch in bimodal listeners. The results also reinforce the conclusion that an temporal alignment of processing delays is mostly beneficial to bimodal users. To investigate the reasons for the decrease in localization accuracy at some loudspeaker positions further research needs to be conducted with longer familiarization periods applied. Further investigations on the influence of asymmetric processing delays on other binaural mechanisms like spatial release from masking could reinforce the hypothesis that temporal synchronization between CI and HA may be necessary for optimal treatment.

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